

12 Math Cheat Sheet

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Part I

Relations and Functions

1 Relations

1.1 Reflexive

$$aRa$$

1.2 Symmetric

$$aRb \implies bRa$$

1.3 Transitive

$$aRb \wedge bRc \implies aRc$$

1.4 Equivalence

If a relation is *reflexive*, *symmetric* and *transitive*, it is an equivalence relation.

2 Functions

2.1 One-one (injection)

If $f(a) = f(b) \implies a = b$, $f(x)$ is a one-one function.

2.2 Onto (surjection)

A function $f : A \rightarrow B$ is onto if every element of B has a pre-image in A .

2.3 Bijection

A function $f(x)$ is a bijection if it is both one-one and onto.

2.4 Composition

$$(f \circ g)(x) = f(g(x))$$

$$(g \circ f)(x) = g(f(x))$$

2.5 Inverse

- Function must be one-one.
- Horizontal line test.
- Reflection in $y = x$.
- If $f : A \rightarrow B$, $f^{-1} : B \rightarrow A$.

$$f(f^{-1}(x)) = f^{-1}(f(x)) = x$$

3 Binary Operations

Number of binary operations = n^{n^2}

3.1 Properties

3.1.1 Commutative

$$a * b = b * a$$

3.1.2 Associative

$$a * (b * c) = (a * b) * c$$

3.1.3 Distributive Law

$$a * (b \odot c) = (a * b) \odot (a * c)$$

3.2 Identity Element

$e \in S$ is the identity element wrt $*$ on S if the following holds for every $x \in S$.

$$e * x = x * e = x$$

4 Inverse Trigonometric Functions

$$\csc^{-1} x = \sin^{-1} \frac{1}{x}$$

$$\sec^{-1} x = \cos^{-1} \frac{1}{x}$$

$$\cot^{-1} x = \begin{cases} \tan^{-1} \frac{1}{x} & x > 0 \\ \pi + \tan^{-1} \frac{1}{x} & x < 0 \end{cases}$$

$$\sin^{-1}(-x) = -\sin^{-1} x$$

$$\csc^{-1}(-x) = -\csc^{-1} x$$

$$\tan^{-1}(-x) = -\tan^{-1} x$$

$$\cos^{-1}(-x) = \pi - \cos x$$

$$\sec^{-1}(-x) = \pi - \sec x$$

$$\cot^{-1}(-x) = \pi - \cot x$$

$$\sin^{-1} x + \cos^{-1} x = \frac{\pi}{2}$$

$$\tan^{-1} x + \cot^{-1} x = \frac{\pi}{2}$$

$$\csc^{-1} x + \sec^{-1} x = \frac{\pi}{2}$$

If $xy < 1$,

$$\tan^{-1} x + \tan^{-1} y = \tan^{-1} \frac{x+y}{1-xy}$$

If $xy > -1$,

$$\tan^{-1} x - \tan^{-1} y = \tan^{-1} \frac{x-y}{1+xy}$$

If $x^2 < 1$,

$$2 \tan^{-1} x = \tan^{-1} \frac{2x}{1-x^2} = \sin^{-1} \frac{2x}{1+x^2} = \cos^{-1} \frac{1-x^2}{1+x^2}$$

$$2 \sin^{-1} x = \sin^{-1} \left(2x\sqrt{1-x^2} \right)$$

$$2 \cos^{-1} x = \cos^{-1} (2x^2 - 1)$$

$$3 \sin^{-1} x = \sin^{-1} (3x - 4x^3)$$

$$3 \cos^{-1} x = \cos^{-1} (4x^3 - 3x)$$

$$3 \tan^{-1} x = \tan^{-1} \frac{3x - x^3}{1 - 3x^2}$$

If <conditions>,

$$\sin^{-1} x + \sin^{-1} y = \sin^{-1} \left(x\sqrt{1-y^2} + y\sqrt{1-x^2} \right)$$

If <conditions>,

$$\sin^{-1} x - \sin^{-1} y = \sin^{-1} \left(x\sqrt{1-y^2} - y\sqrt{1-x^2} \right)$$

$$\cos^{-1} x + \cos^{-1} y = \cos^{-1} \left(xy - \sqrt{1-x^2} \cdot \sqrt{1-y^2} \right)$$

Part II

Algebra

5 Determinants

$$\begin{vmatrix} \cdot & \cdot & \cdot \\ 0 & 0 & 0 \\ \cdot & \cdot & \cdot \end{vmatrix} = 0$$

$$\begin{vmatrix} \rightarrow & \rightarrow & \rightarrow \\ \rightarrow & \rightarrow & \rightarrow \\ \rightarrow & \rightarrow & \rightarrow \end{vmatrix} = \begin{vmatrix} \downarrow & \downarrow & \downarrow \\ \downarrow & \downarrow & \downarrow \\ \downarrow & \downarrow & \downarrow \end{vmatrix}$$

$$\begin{vmatrix} a & d & \cdot \\ b & e & \cdot \\ c & f & \cdot \end{vmatrix} = - \begin{vmatrix} d & a & \cdot \\ e & b & \cdot \\ f & c & \cdot \end{vmatrix}$$

$$\begin{vmatrix} a & b & c \\ a & b & c \\ \cdot & \cdot & \cdot \end{vmatrix} = 0$$

$$\begin{vmatrix} ka & kb & kc \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix} = k \begin{vmatrix} a & b & c \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix}$$

$$\begin{vmatrix} a+x & \cdot & \cdot \\ b+y & \cdot & \cdot \\ c+z & \cdot & \cdot \end{vmatrix} = \begin{vmatrix} a & \cdot & \cdot \\ b & \cdot & \cdot \\ c & \cdot & \cdot \end{vmatrix} + \begin{vmatrix} x & \cdot & \cdot \\ y & \cdot & \cdot \\ z & \cdot & \cdot \end{vmatrix}$$

$$\begin{vmatrix} a & b & c \\ \cdot & \cdot & \cdot \\ g+ka & h+kb & i+kc \end{vmatrix} = \begin{vmatrix} a & b & c \\ \cdot & \cdot & \cdot \\ g & h & i \end{vmatrix}$$

$$\begin{vmatrix} a + ld + mg & d & g \\ b + le + mh & e & h \\ c + lf + mi & f & i \end{vmatrix} = \begin{vmatrix} a & d & g \\ b & e & h \\ c & f & i \end{vmatrix}$$

$$\begin{vmatrix} 1 & 1 & 1 \\ a & b & c \\ a^3 & b^3 & c^3 \end{vmatrix} = (a - b)(b - c)(c - a)(a + b + c)$$

6 Matrices

6.1 Adjoint

$$\text{adj} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\text{adj} \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = \begin{bmatrix} + \begin{vmatrix} e & f \\ h & i \end{vmatrix} & - \begin{vmatrix} d & f \\ g & i \end{vmatrix} & + \begin{vmatrix} d & e \\ g & h \end{vmatrix} \\ - \begin{vmatrix} b & c \\ h & i \end{vmatrix} & + \begin{vmatrix} a & c \\ g & i \end{vmatrix} & - \begin{vmatrix} a & b \\ g & h \end{vmatrix} \\ + \begin{vmatrix} b & c \\ e & f \end{vmatrix} & - \begin{vmatrix} a & c \\ d & f \end{vmatrix} & + \begin{vmatrix} a & b \\ d & e \end{vmatrix} \end{bmatrix}'$$

6.2 Inverse

A has an inverse only if A is non-singular ($|A| \neq 0$).

$$A^{-1} = \frac{\text{adj} A}{|A|}$$

6.3 Inverse by elementary operations

$$A = IA$$

	Row-wise	Column-wise
1	$R_i \longleftrightarrow R_j$	$C_i \longleftrightarrow C_j$
2	$R_i \rightarrow kR_i$	$C_i \rightarrow kC_i$
3	$R_i \rightarrow R_i + kR_j$	$C_i \rightarrow C_i + kC_j$

6.4 Properties

$$|\text{adj} A| = |A|^2$$

$$(AB)^{-1} = B^{-1}A^{-1}$$

$$(A')^{-1} = (A^{-1})'$$

6.5 Area of a triangle

Vertices: $(x_1, y_1), (x_2, y_2), (x_3, y_3)$.

$$\Delta = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$

6.6 Symmetric and skew-symmetric matrices

$$A = \frac{1}{2}(A + A') + \frac{1}{2}(A - A')$$

$\frac{1}{2}(A + A')$ is symmetric and $\frac{1}{2}(A - A')$ is skew-symmetric.

6.7 Solving equations

6.7.1 Conditions

$ A $	$(\text{adj}A)B$	Singularity	Number of solutions	Consistency
$ A \neq 0$	N.A.	Non-singular	Unique solution	Consistent
$ A = 0$	$(\text{adj}A)B \neq 0$	Singular	No solution	Inconsistent
	$(\text{adj}A)B = 0$		Infinitely many solutions	Consistent

6.7.2 2 variables, 2 equations

$$\begin{aligned} a_1x + b_1y &= p \\ a_2x + b_2y &= q \end{aligned}$$

$$\begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} p \\ q \end{bmatrix}$$

aka $AX = B$

$$X = A^{-1} \times B$$

6.7.3 3 variables, 3 equations

$$a_1x + b_1y + c_1z = p$$

$$a_2x + b_2y + c_2z = q$$

$$a_3x + b_3y + c_3z = r$$

$$\begin{bmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} p \\ q \\ r \end{bmatrix}$$

aka $AX = B$

$$X = A^{-1} \times B$$

Part III

Calculus

7 Continuity and Differentiability of Functions

7.1 Conditions For Continuity

- $f(a)$ is defined
- $\lim_{x \rightarrow a} f(x)$ exists
- $\lim_{x \rightarrow a} f(x) = f(a)$

7.2 Conditions For Differentiability

$$Rf'(a) = \lim_{h \rightarrow 0} \frac{f(a+h) - f(a)}{h}$$

$$Lf'(a) = \lim_{h \rightarrow 0} \frac{f(a-h) - f(a)}{-h}$$

$f(x)$ is differentiable at $x = a$ if $Rf'(a) = Lf'(a)$

8 Differentiation

$$\frac{d}{dx}(\text{constant}) = 0$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(e^x) = e^x$$

$$\frac{d}{dx}(a^x) = a^x \ln a$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(\log_a x) = \frac{1}{x \ln a}$$

$$\frac{d}{dx}(uv) = u'v + uv'$$

$$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{vu' - uv'}{v^2}$$

$$\frac{dy}{dx} = \frac{1}{\frac{dx}{dy}}$$

$$\frac{dy}{dx} = \frac{dy}{dt} \times \frac{dt}{dx}$$

$$\frac{d}{dx}|x| = \frac{x}{|x|}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\frac{d}{dx}(\tan x) = \sec^2 x$$

$$\frac{d}{dx}(\cot x) = -\csc^2 x$$

$$\frac{d}{dx}(\sec x) = \sec x \tan x$$

$$\frac{d}{dx}(\csc x) = \csc x \cot x$$

$$\frac{d}{dx}(\sin^{-1} x) = \frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\cos^{-1} x) = \frac{-1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx}(\tan^{-1} x) = \frac{1}{1+x^2}$$

$$\frac{d}{dx}(\cot^{-1} x) = \frac{-1}{1+x^2}$$

$$\frac{d}{dx}(\sec^{-1} x) = \frac{1}{|x|\sqrt{x^2-1}}$$

$$\frac{d}{dx}(\csc^{-1} x) = \frac{-1}{|x|\sqrt{x^2-1}}$$

If $y = [f(x)]^{g(x)}$, take the logarithm of both sides and then differentiate.

Table 1: Differentiation by substitution

Expression	Substitution to perform
$a^2 - x^2$	Put $x = a \sin t$ or $x = a \cos t$
$a^2 + x^2$	Put $x = a \tan t$ or $x = a \cot t$
$x^2 - a^2$	Put $x = a \sec t$ or $x = a \csc t$
$\sqrt{\frac{a-x}{a+x}}$ or $\sqrt{\frac{a+x}{a-x}}$	Put $x = a \cos t$
$a \cos x \pm b \sin x$	Put $a = r \cos \alpha$, $b = r \sin \alpha$

9 Indeterminate Forms of Limits

10 Mean Value Theorems

10.1 Rolle's Theorem

If $f(x)$ satisfies the following conditions:

- $f(x)$ is continuous in the *closed* interval $[a, b]$
- $f(x)$ is derivable in the *open* interval (a, b)
- $f(a) = f(b)$

... then there exists at least one real number $x = c$ in the *open* interval (a, b) such that $f'(c) = 0$.

10.2 Langrange's Mean Value Theorem

If a function $f(x)$ defined in the closed interval $[a, b]$ satisfies the following conditions:

- $f(x)$ is continuous in the *closed* interval $[a, b]$
- $f(x)$ is derivable in the *open* interval (a, b)

... there exists at least one value of x , c , in the *open* interval (a, b) such that $f'(c) = \frac{f(b)-f(a)}{b-a}$.

11 Applications of Derivatives

11.1 Tangents and Normals

$$m = \frac{dy}{dx}(x')$$

$$y - y' = m(x - x')$$

$$y - y' = -\frac{1}{m}(x - x')$$

11.2 Approximations

$$\delta y = \frac{dy}{dx}(x') \times \delta x$$

11.3 Rate Measuring

$$\text{Rate of change of } y = \frac{dy}{dx} \times \text{Rate of change of } x$$

$$\frac{dy}{dx} = \frac{dy}{dt} \times \frac{dt}{dx}$$

11.4 Monotonicity

$$\frac{dy}{dx} \begin{cases} > 0 & \tan \psi \text{ is acute} \\ < 0 & \tan \psi \text{ is obtuse} \\ = 0 & \tan \psi = \psi = 0 \\ \text{is undefined} & \psi = 90^\circ \end{cases}$$

$$f(x) \begin{cases} \text{increasing} & f'(x) > 0 \\ \text{decreasing} & f'(x) < 0 \\ \text{constant} & f'(x) = 0 \end{cases}$$

12 Maxima and Minima

$$\frac{dy}{dx} = 0$$

Minima	Maxima
$\frac{d^2y}{dx^2} > 0$	$\frac{d^2y}{dx^2} < 0$
$\frac{dy}{dx}$ goes from $-$ to $+$	$\frac{dy}{dx}$ goes from $+$ to $-$

13 Indefinite Integrals — Standard Forms

$$\int x^n dx = \frac{x^{n+1}}{n+1} + C$$

$$\int (ax+b)^n dx = \frac{(ax+b)^{n+1}}{(n+1)a} + C$$

$$\int \cos x dx = \sin x + C$$

$$\int \sin x dx = -\cos x + C$$

$$\int \sec^2 x dx = \tan x + C$$

$$\int \csc^2 x dx = -\cot x + C$$

$$\int \csc x \cot x dx = -\csc x + C$$

$$\int \sec x \tan x dx = \sec x + C$$

$$\int \tan x dx = \ln |\sec x| + C$$

$$\int \cot x dx = \ln |\sin x| + C$$

$$\int \csc x dx = \ln |\csc x - \cot x| + C = \ln \left| \tan \frac{x}{2} \right| + C$$

$$\int \sec x dx = \ln |\sec x + \tan x| + C = \ln \left| \tan \left(\frac{\pi}{4} + \frac{x}{2} \right) \right| + C$$

14 Indefinite Integrals — Methods of Integration

$$\int \frac{1}{\sqrt{1-x^2}} dx = \sin^{-1} x + C$$

$$\int \frac{-1}{\sqrt{1-x^2}} dx = \cos^{-1} x + C$$

$$\int \frac{1}{1+x^2} dx = \tan^{-1} x + C$$

$$\int \frac{-1}{1+x^2} dx = \cot^{-1} x + C$$

$$\int \frac{1}{|x|\sqrt{x^2-1}} dx = \sec^{-1} x + C$$

$$\int \frac{-1}{|x|\sqrt{x^2-1}} dx = \csc^{-1} x + C$$

$$\int e^x [f(x) + f'(x)] dx = e^x \cdot f(x) + C$$

$$\int (f \cdot g) dx = f \int g dx - \int \left[f' \int g dx \right] dx$$

15 Indefinite Integrals — Special Integrals

$$\int \frac{dx}{x^2 + a^2} = \frac{1}{a} \tan^{-1} \frac{x}{a} + C$$

$$\int \frac{dx}{x^2 - a^2} = \frac{1}{2a} \ln \left| \frac{x-a}{x+a} \right| + C$$

$$\int \frac{dx}{a^2 - x^2} = \frac{1}{2a} \ln \left| \frac{a+x}{a-x} \right| + C$$

$$\int \frac{dx}{\sqrt{x^2 \pm a^2}} = \ln \left| x + \sqrt{x^2 \pm a^2} \right| + C$$

$$\int \frac{dx}{\sqrt{a^2 - x^2}} = \sin^{-1} \frac{x}{a} + C$$

$$\int \sqrt{x^2 \pm a^2} dx = \frac{x}{2} \sqrt{x^2 \pm a^2} \pm \frac{a^2}{2} \ln \left| x + \sqrt{x^2 \pm a^2} \right| + C$$

$$\int \sqrt{a^2 - x^2} dx = \frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \frac{x}{a} + C$$

15.1 $\int \sqrt{ax^2 + bx + c} dx, \int (px + q)\sqrt{ax^2 + bx + c} dx$

15.2 $\int \frac{a \sin x + b \cos x}{c \sin x + d \cos x} dx$

Let A and B be constants. If N is the numerator and D is the denominator, set:

$$N = A(D) + B \frac{d}{dx}(D)$$

15.3 $\int \frac{x^2 \pm 1}{x^4 + kx^2 + 1} dx \quad (k \text{ may be } 0)$

Divide numerator and denominator by x^2 . Let $t = x + \frac{1}{x}$ or $t = x - \frac{1}{x}$ depending on which t gives the numerator of the resulting integrand on differentiation.

$$15.4 \quad \int \frac{dx}{a+b\cos x}, \int \frac{dx}{a+b\sin x}, \int \frac{dx}{a\cos x+b\sin x}, \int \frac{dx}{a\cos x+b\sin x+c}$$

- Substitute $\sin x = \frac{2\tan \frac{x}{2}}{a+\tan^2 \frac{x}{2}}$, $\cos x = \frac{1-\tan^2 \frac{x}{2}}{1+\tan^2 \frac{x}{2}}$.
- Replace $1 + \tan^2 \frac{x}{2}$ in the numerator with $\sec^2 \frac{x}{2}$.
- Substitute $t = \tan \frac{x}{2}$, $dt = \frac{1}{2} \sec^2 \frac{x}{2}$

$$15.5 \quad \int \frac{dx}{a\cos^2 x+b\sin^2 x+c}$$

$$15.6 \quad \int \frac{dx}{1+x^4}$$

$$15.7 \quad \int \sqrt{\tan x} dx, \int \sqrt{\cot x} dx$$

16 Definite Integrals

$$\int_a^b f(x)dx = \int_a^b f(t)dt$$

$$\int_a^b f(x)dx = - \int_b^a f(x)dx$$

$$\int_a^a f(x)dx = 0$$

$$\int_a^c f(x)dx = \int_a^b f(x)dx + \int_b^c f(x)dx$$

$$\int_a^b f(x)dx = \int_a^b f(a+b-x)dx$$

$$\int_0^a f(x)dx = \int_0^a f(a-x)dx$$

$$\int_0^{2a} f(x)dx = \int_0^a f(x)dx + \int_0^a f(2a-x)dx$$

$$\int_0^{2a} f(x)dx = \begin{cases} 2 \int_0^a f(x)dx & f(2a-x) = f(x) \\ 0 & f(2a-x) = -f(x) \end{cases}$$

$$\int_{-a}^a f(x)dx = \begin{cases} 2 \int_0^a f(x)dx & f(-x) = f(x) \\ 0 & f(-x) = -f(x) \end{cases}$$

17 Definite Integral as a limit of a sum

$$\int_a^b f(x)dx = \lim_{h \rightarrow 0} h [f(a) + f(a+h) + f(a+2h) + \dots + f(a+(n-1)h)]$$

$$nh = b - a$$

$$1 + 2 + \cdots + n = \frac{n(n+1)}{2}$$

$$1^2 + 2^2 + \cdots + n^2 = \frac{n(n+1)(2n+1)}{6}$$

$$1^3 + 2^3 + \cdots + n^3 = \left(\frac{n(n+1)}{2} \right)^2$$

$$\sin a + \sin(a+h) + \sin(a+2h) + \cdots + \sin(a+(n-1)h) = \frac{\sin \left\{ a + \frac{n-1}{2}h \right\} \sin \frac{nh}{2}}{\sin \frac{h}{2}}$$

$$\cos a + \cos(a+h) + \cos(a+2h) + \cdots + \cos(a+(n-1)h) = \frac{\cos \left\{ a + \frac{n-1}{2}h \right\} \cos \frac{nh}{2}}{\cos \frac{h}{2}}$$

18 Differential Equations

18.1 Variable Separable

$$18.1.1 \quad \frac{dy}{dx} = f(x)$$

$$18.1.2 \quad \frac{dy}{dx} = f(y)$$

$$18.1.3 \quad \frac{dy}{dx} = f(x) \cdot \phi(y)$$

$$18.1.4 \quad \frac{dy}{dx} = f(ax + by + c)$$

18.2 Reducible to Variable Separable

18.3 Homogeneous equations of first order

$$18.3.1 \quad \frac{dy}{dx} = \frac{f(x,y)}{g(x,y)} = m\left(\frac{y}{x}\right)$$

$$y = vx$$

$$\frac{dy}{dx} = v + x \frac{dv}{dx}$$

18.4 Linear equations

$$18.4.1 \quad \frac{dy}{dx} + Py = Q$$

$$\text{IF} = e^{\int P dx}$$

$$y \cdot \text{IF} = \int (Q \cdot \text{IF}) dx + C$$

Part IV

Probability

19 Probability

$$P(\bar{A}) = 1 - P(A)$$

$$P(A/B) = \frac{n(A \cap B)}{n(B)}$$

$$P(A \cap B) = P(B) \times P(A/B) = P(A) \times P(B/A)$$

19.1 A and B are mutually exclusive

$$P(A \cap B) = 0$$

19.2 A and B are independent events

$$P(A/B) = P(A)$$

$$P(B/A) = P(B)$$

$$P(A \cap B) = P(A) \times P(B)$$

19.3 Geometric Progression

$$a + ar + ar^2 + \cdots = \frac{a}{1 - r}$$

20 Bayes' Theorem

$$P(E_1/A) = \frac{P(E_1) \cdot P(A/E_1)}{P(E_1) \cdot P(A/E_1) + P(E_2) \cdot P(A/E_2)}$$

$$P(E_1/A) = \frac{P(E_1) \cdot P(A/E_1)}{P(E_1) \cdot P(A/E_1) + P(E_2) \cdot P(A/E_2) + P(E_3) \cdot P(A/E_3)}$$

21 Theoretical Probability Distribution

$$\int_{-\infty}^{\infty} f(x) \cdot dx = 1$$

$$\bar{x} = \sum_{i=1}^n p_i x_i = \sum_{i=1}^n x_i f(x)$$

$$\sigma^2 = \sum_{i=1}^n p_i \cdot x_i^2 - \bar{x}^2 = \sum_{i=1}^n p_i (x_i - \bar{x})^2$$

$$\sigma = +\sqrt{\sigma^2}$$

21.1 Binomial Distribution

$$P(r) = \binom{n}{r} q^{n-r} p^r$$

$$\mu = np$$

$$\sigma^2 = npq$$

Part V

Vectors

22 Vectors

23 Vectors (Continued)

Part VI

Three-Dimensional Geometry

24 Three-Dimensional Geometry

25 The Plane

Part VII

Application of Integrals

26 Areas of a Curve

Part VIII

Application of Calculus

27 Application of Calculus in Commerce and Economics

$$C(x) = F + V(X)$$

$$\text{AC} = \frac{C(x)}{x} = \text{AFC} + \text{AVC}$$

$$R = px$$

$$P(x) = R(x) - C(x)$$

At the break-even point (say x_b),

$$R(x_b) = C(x_b)$$

$$\text{MC} = \frac{d}{dx} [C(x)] = \frac{dC}{dx}$$

$$\text{AFC} = \frac{\text{TFC}}{Q}$$

$$\text{AVC} = \frac{\text{TVC}}{Q}$$

$$\frac{d}{dx}(\text{AC}) = \frac{1}{x}(\text{MC} - \text{AC})$$

$$C=\int \mathbf{MC}\cdot\mathrm{d}x$$

$$C_d = \int_0^d \mathbf{MC} \cdot \mathrm{d}x$$

$$R=\int \mathbf{MR}\cdot\mathrm{d}x$$

$$R_d = \int_0^d \mathbf{MR} \cdot \mathrm{d}x$$

Part IX

Linear Regression

28 Linear Regression

dependent on independent

$$d_x = x_i - \bar{x}$$

$$d_y = y_i - \bar{y}$$

	y on x	x on y
Regression line	$y - \bar{y} = b_{yx}(x - \bar{x})$	$x - \bar{x} = b_{xy}(y - \bar{y})$
Normal Equations	$\sum y = nc + m \sum x$	$\sum x = nc + m \sum y$
	$\sum xy = c \sum x + m \sum x^2$	$\sum xy = c \sum y + m \sum y^2$
Regression Coefficient	$b_{yx} = r \frac{\sigma_y}{\sigma_x}$	$b_{xy} = r \frac{\sigma_x}{\sigma_y}$
When deviations are taken from the mean	$b_{yx} = \frac{\sum d_x d_y}{\sum d_x^2}$	$b_{xy} = \frac{\sum d_x d_y}{\sum d_y^2}$
When deviations are taken from the assumed mean	$b_{yx} = \frac{\sum d_x d_y - \frac{\sum d_x \sum d_y}{n}}{\sum d_x^2 - \frac{(\sum d_x)^2}{n}}$	$b_{xy} = \frac{\sum d_x d_y - \frac{\sum d_x \sum d_y}{n}}{\sum d_y^2 - \frac{(\sum d_y)^2}{n}}$
When original values are used	$b_{yx} = \frac{\sum xy - \frac{\sum x \sum y}{n}}{\sum x^2 - \frac{(\sum x)^2}{n}}$	$b_{xy} = \frac{\sum xy - \frac{\sum x \sum y}{n}}{\sum y^2 - \frac{(\sum y)^2}{n}}$

$$r = \pm \sqrt{b_{yx} \cdot b_{xy}}$$

$$r^2 \leq 1$$

$$r = \frac{\sum (d_x d_y)}{\sqrt{\sum d_x^2 \times \sum d_y^2}}$$

Point of intersection of the two regression lines is (\bar{x}, \bar{y}) .

Part X

Linear Programming

29 Linear Programming

Part XI

Appendices

A Useful Trigonometric Formulae

B Other Useful Formulae

$$a^3 \pm b^3 = (a \pm b)(a^2 + ab + b^2)$$